

## 5) Pure Integrals

We have seen that one can construct DE for a basis of Feynman integrals and solve these order-by-order in  $\epsilon$ . At last, we want to discuss how to choose a "good" basis, such that the DE simplifies.

### 5.1 Uniform Transcendality

Let us introduce the concept of "uniform transcendality" (UT).

We call an integral with expansion

$$I_i = \epsilon^{-m} \sum_{n=0}^{\infty} \epsilon^n I_i^{(n)}$$

with  $m$  a fixed integer and  $I_i^{(n)}$  a pure function of transcendental weight  $n$ , a UT integral. The transcendental weight is defined by

$$T(\text{rational number}) = 0, \quad T(\pi) = 1, \quad T(\zeta(n)) = n$$

$$T(\text{rational function}) = 0, \quad T(\log(x)) = 1, \quad T(\text{Li}_n(x)) = n$$

and the product is defined by

$$T(f_1 f_2) = T(f_1) + T(f_2).$$

Thus, a pure integral has the properties

$$T(I_i^{(n)}) = n, \quad T\left(\frac{\partial I_i^{(n)}}{\partial x}\right) = n-1$$

Clearly, the integrals we have considered before are not pure! For a basis of UT integrals the differential equation takes the form

$$\frac{\partial \vec{I}}{\partial x_i} = \epsilon A_i(x) \vec{I}$$

"canonical DE"

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The integrability condition simplifies to

$$[A_i, A_j] = 0, \quad \left(\frac{\partial A_i}{\partial x_j} - \frac{\partial A_j}{\partial x_i}\right) = 0$$

The latter condition can be read as path-independence ( $\nabla \times \vec{A} = 0$ ), which tells us that one can write  $\vec{A}$  as a gradient field

$$A_i = \frac{\partial}{\partial x_j} \sum_{\alpha} M_{\alpha} \log(w_{\alpha})$$

↖ functions of kinematics

↖ Matrix with rational numbers

## 5.2 Pure one-loop Basis

At one-loop a general recipe exist to construct a  $\overline{\text{UT}}$  basis. We choose the master integrals according to

Topology	Dimension	Prefactor
Tadpole	$2-2\epsilon$	$\epsilon$
Bubble	$2-2\epsilon$	$\epsilon$
Triangle	$4-2\epsilon$	$\epsilon^2$
Box	$4-2\epsilon$	$\epsilon^2$
Pentagon	$6-2\epsilon$	$\epsilon^2$

These basis integrals still need to be multiplied by a kinematic prefactor, that we will discuss in the following. However, for practical purposes one would like to use integrals in  $d=4-2\epsilon$ . One can show that

$$i^2 \text{Bubble} \Big|_{d=2-2\epsilon} = - \left( \text{Bubble} + \text{Bubble} \right) \Big|_{d=4-2\epsilon} = \frac{2}{2} a^{\frac{2}{2}(1-2\epsilon)} \text{Bubble} \Big|_{d=4-2\epsilon}$$

$\leftarrow$  massless Bubble

where we have dropped a kinematic dependent factor, rational prefactor

For our example we therefore define

$$J_1 = e^{1/\epsilon} \underbrace{(-s)^{\epsilon}}_{\text{Dim. less}} \underbrace{\frac{2(1-2\epsilon)}{\epsilon}}_{\text{Dim shift}} \epsilon \underbrace{I_1}_{\text{Prefactor}} \leftarrow d=4-2\epsilon \text{ master}$$

$$J_2 = e^{1/\epsilon} (-s)^{\epsilon} \frac{2(1-2\epsilon)}{\epsilon} \epsilon I_2$$

$$J_3 = e^{1/\epsilon} (-s)^{2+\epsilon} \epsilon^2 I_3$$

which can be written

$$\text{as } \vec{J} = T \vec{I}$$

In this basis the DE takes the form

$$B_s = T A_s T^{-1} + \frac{\partial T}{\partial s} T^{-1} = \underbrace{\begin{pmatrix} -\frac{1}{s} & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1/s \end{pmatrix}}_{B_s^{(0)}} + \epsilon \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & 1/s & 0 \\ \frac{\epsilon s}{s+\epsilon} & \frac{-\epsilon s}{s+\epsilon} & \frac{1}{s+\epsilon} \end{pmatrix}}_{B_s^{(1)}}$$

$$B_\epsilon = T A_\epsilon T^{-1} + \frac{\partial T}{\partial \epsilon} T^{-1} = \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & -1/\epsilon & 0 \\ 0 & 0 & -1/\epsilon \end{pmatrix}}_{B_\epsilon^{(0)}} + \epsilon \underbrace{\begin{pmatrix} 0 & 0 & 0 \\ 0 & -1/\epsilon & 0 \\ \frac{-\epsilon s^2}{\epsilon(s+\epsilon)} & \frac{\epsilon s^2}{\epsilon(s+\epsilon)} & \frac{-s}{\epsilon(s+\epsilon)} \end{pmatrix}}_{B_\epsilon^{(1)}}$$

The DE is still not canonical but we can perform a second transformation  $\vec{J}' = T_2 \vec{J}$

$$T_2 = \exp\left(-\int ds B_s^{(0)}\right) \exp\left(-\int d\epsilon B_\epsilon^{(0)}\right) = \begin{pmatrix} s & & \\ & \epsilon & \\ & & \epsilon/s \end{pmatrix},$$

which brings the DE in canonical form.

$$B_s' = \epsilon \begin{pmatrix} 0 & 0 & 0 \\ 0 & 1/s & 0 \\ \frac{\epsilon}{s(s+\epsilon)} & \frac{-1}{s+\epsilon} & \frac{1}{s+\epsilon} \end{pmatrix}, \quad B_\epsilon' = \epsilon \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1/\epsilon & 0 \\ \frac{-1}{s+\epsilon} & \frac{s}{\epsilon(s+\epsilon)} & \frac{-s}{\epsilon(s+\epsilon)} \end{pmatrix}$$

Introducing again  $\epsilon = X S$

$$\left(\frac{\partial \vec{J}'}{\partial S}\right)_X = 0, \quad \left(\frac{\partial \vec{J}'}{\partial X}\right)_S = \epsilon \left[ \frac{1}{X} \begin{pmatrix} 0 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 1 & -1 \end{pmatrix} + \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ -1 & -1 & 1 \end{pmatrix} \frac{1}{1+X} \right] \vec{J}'$$

As before  $J_1'$  decouples and explicit integration yields

$$J_1' = 2 - \frac{\pi^2}{6} \epsilon^2 - \frac{14}{3} \zeta(3) \epsilon^3 - \frac{47}{720} \pi^4 \epsilon^4 + \left[ \frac{7}{18} \pi^2 \zeta(3) - \frac{62}{5} \zeta(5) \right] \epsilon^5 + O(\epsilon^6)$$

$\Rightarrow J_1'$  is a UT integral!

For  $J_2'$  we also find again

$$\frac{\partial J_2'}{\partial X} = -\frac{\epsilon}{X} J_2' \Rightarrow \boxed{J_2' = B X^{-\epsilon} = J_1' X^{-\epsilon}}$$

$$J_2' = 2 - 2 \log(x) \epsilon + \left[ -\frac{\pi^2}{6} + \log^2(x) \right] \epsilon^2 + \frac{1}{6} \left[ \pi^2 \log(x) - 2 \log^3(x) - 28 \zeta(3) \right] \epsilon^3 + \dots$$

$\Rightarrow J_2'$  is a UT integral!

The biggest difference occurs for the Box integral. When solving the DE again order-by-order in  $\epsilon$  it reads

$$\frac{\vec{J}}{\partial x} = A_x^{(n)} \vec{J}^{(n-1)}$$

which, compared to our first approach, has no homogeneous part and can be simply differentiated

$$\vec{J}^{(n)} = \vec{B}^{(n)} + \int dx A_x^{(n)} \vec{J}^{(n-1)}$$

For the Box-integral we explicitly have

$$J_3^{(n)} = B^{(n)} + \int dx \frac{1}{x} [J_2^{(n-1)} - J_3^{(n-1)}] + \int dx \frac{1}{1+x} \underbrace{\left[ -J_1^{(n-1)} - J_2^{(n-1)} + J_3^{(n-1)} \right]}_{\text{will always determine } B^{(n-1)}}$$

We find

$$n=0: J_3^{(0)} = B^{(0)}$$

$$n=1: J_3^{(1)} = B^{(1)} + \int dx \frac{1}{x} [2 - B^{(0)}] + \int dx \frac{1}{1+x} \underbrace{[-4 + B^{(0)}]}_{\Rightarrow B^{(0)} = 4 \text{ finite at } x=-1}$$

$$= B^{(1)} + \int dx \frac{-2}{x} = B^{(1)} - 2 \log(x)$$

$$n=2: J_3^{(2)} = B^{(2)} + \int dx \frac{1}{x} [-2 \log(x) - B^{(1)} + 2 \log(x)] + \int dx \frac{B^{(1)}}{1+x}$$

$$= B^{(2)} \quad \underbrace{\quad}_{\Rightarrow B^{(1)} = 0}$$

and so on. We find

$$J_3 = 4 - 2 \log(x) \epsilon - \frac{4\pi^2}{3} \epsilon^2 + \left[ \frac{7\pi^2}{6} \log(x) + \frac{1}{3} \log^3(x) - (\pi^2 + \log^2(x)) \log(1-x) - 2 \log(x) \text{Li}_2(-x) + 2 \text{Li}_3(-x) - \frac{34}{3} \zeta(3) \right] \epsilon^3 + \dots$$

which is a UT!